Assessing Surface Textural Variations on the Piton de La Fournaise Volcano Using L-Band InSAR and LiDAR Fusion Study

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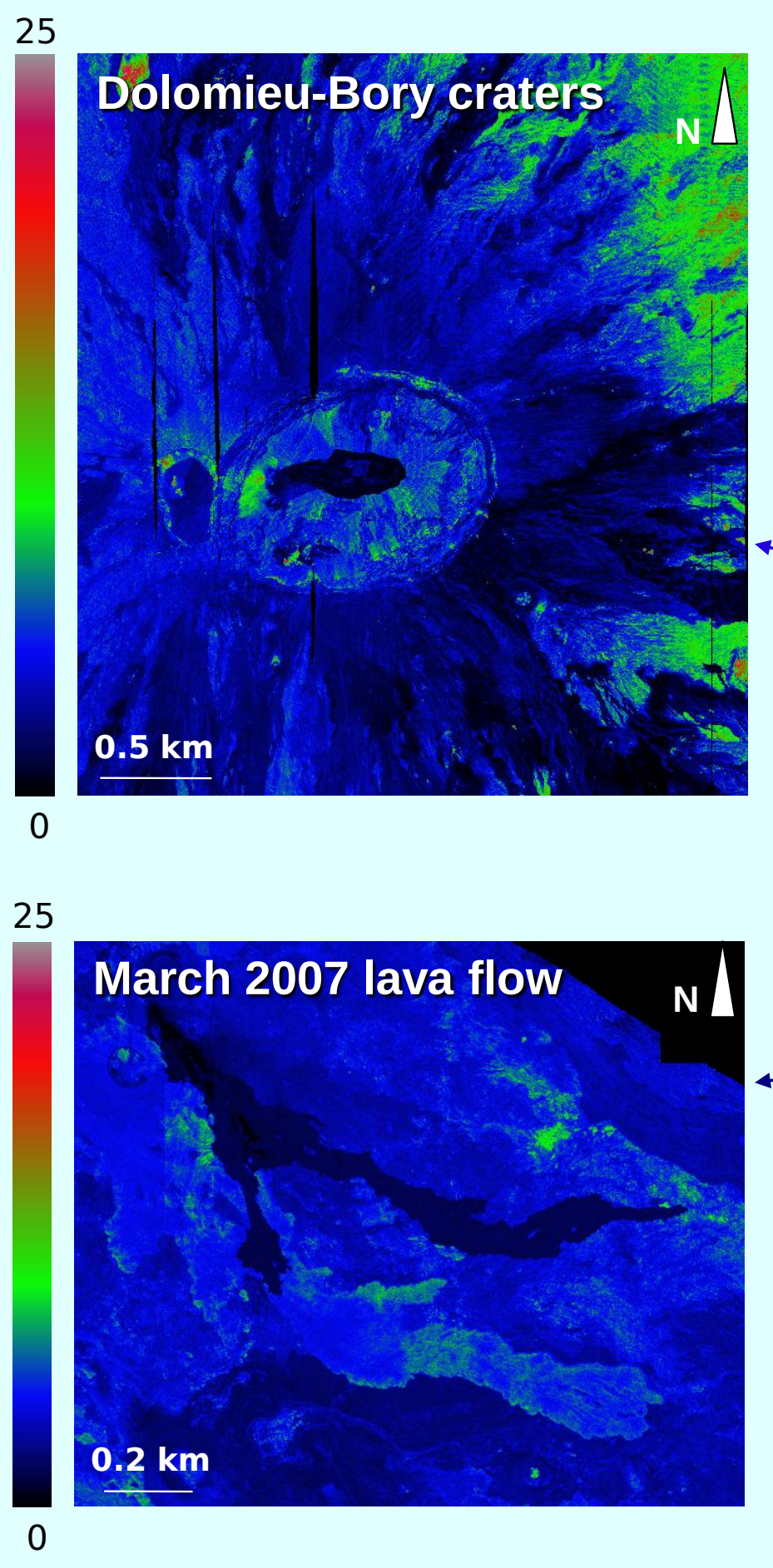
- The Piton de La Fournaise is a very active volcano with an eruption around every 8 months [1].
- Interferometric synthetic aperture radar (InSAR) is a powerful tool to monitor deformation in active volcanoes.
- InSAR lacks accuracy over vegetated and pyroclastic surfaces that induce radar phase decorrelation and then errors of pre-eruptive surface displacements [2].
- Light detection and ranging (LiDAR) technology provides more accurate information about topography and vegetation height and allows to generate a high-resolution digital terrain model (DTM) of the volcanic edifice. The information derived from intensity values was recently used to identify and map lava flows [3,4].
- To enhance the calculation of InSAR coherence, we combine normalized airborne LiDAR intensity data with spaceborne InSAR coherence images from ALOS PALSAR L-band acquired over the Piton de la Fournaise in 2008 and 2009.
- This study is focused on different lava flows, vegetated and pyroclastic surfaces.

LiDAR data processing

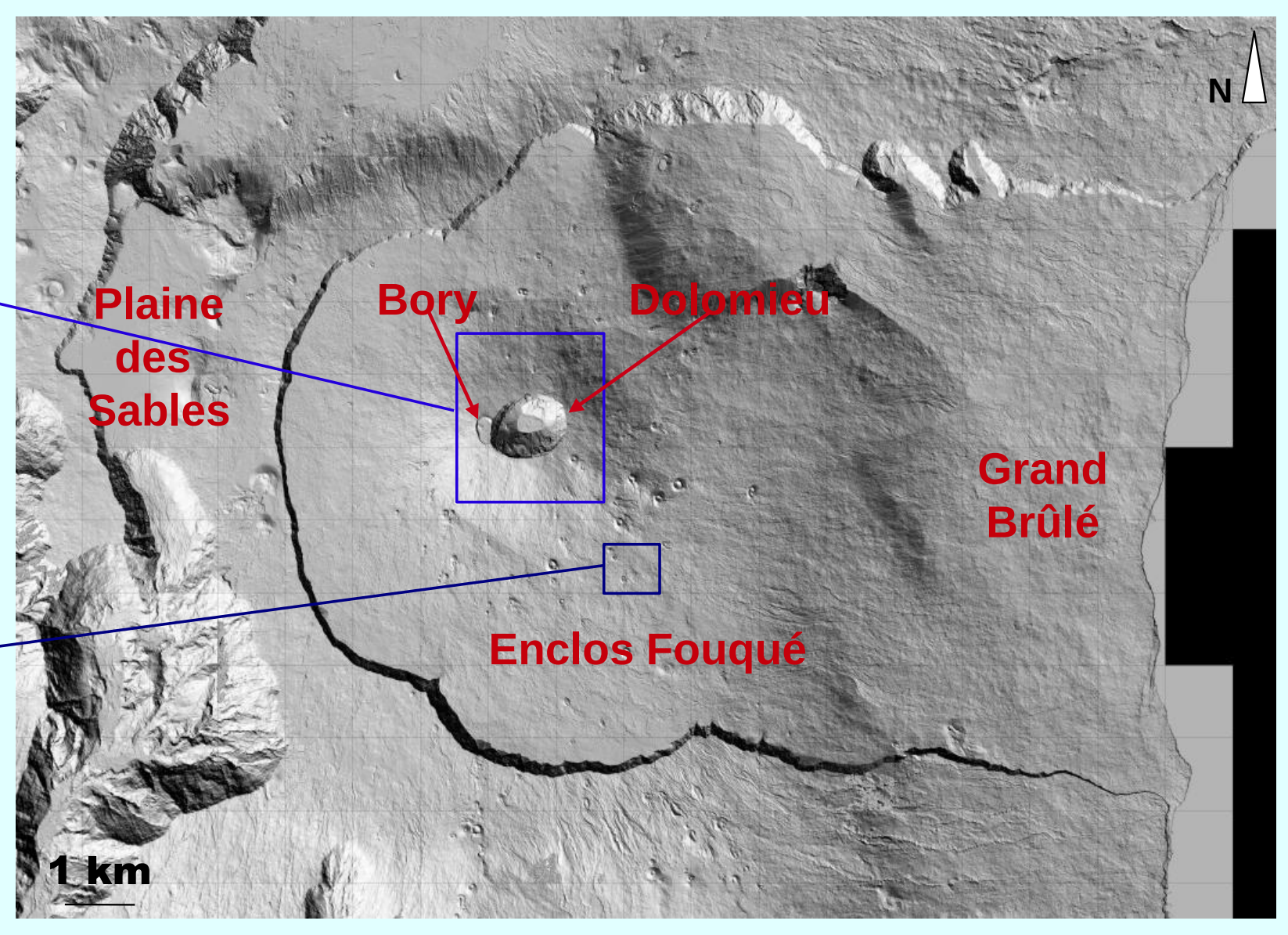
Datasets (IGN)

- Two high-resolution airborne campaigns performed over the volcano in 2008 and 2009
- Two low-resolution airborne campaigns performed along the island shore in 2008 and over the whole island in 2009



Acquisition system

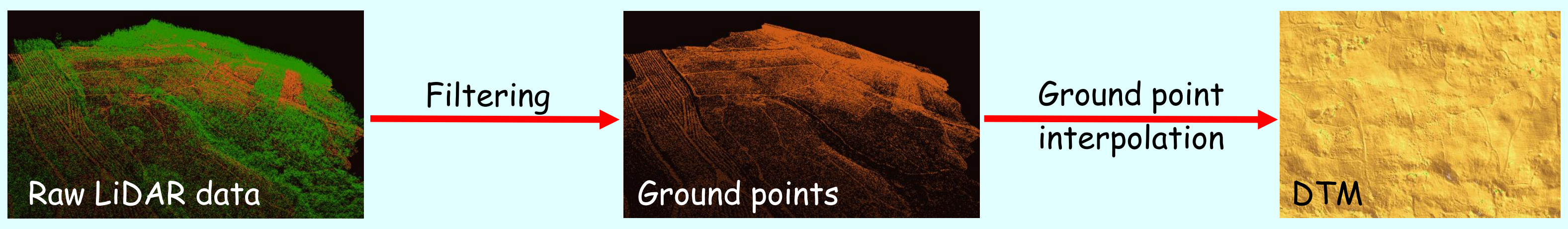
Wavelength	1064 nm
Vertical accuracy	< 0.15 m
Horizontal accuracy	< 0.40 m
Density	1-5 pt/m²
Scan angle	5-10°
Measurement rate	50 kHz
Flight height	~1400 m (AGL)



Shaded relief of the volcano derived from the LiDAR data (spatial resolution = 1m); On the left, intensity maps of two regions.

Generation of a DTM

- Filtering of the point cloud to classify the different types of points (low or high vegetation and ground)
- Triangulation of the ground points to generate a DTM with a 1 m resolution by using the Terrascan software (TIN model)



- Validation of the DTM by comparing the GPS (vertical accuracy = 0,05-0,1 m) and the LiDAR data acquired over several regions
  → mean of the differences $|z_{LiDAR} – z_{GPS}|$: $\mu\Delta z = 0,03$ m

Generation of normalized intensity images

- Spatial resampling of the intensity values
- Assessment of the main factors influencing the laser intensity [5,6]
  - a) the distance between the sensor and the target
  - b) the topographic and local scan angle effects
  - c) the atmospheric attenuation (considered as constant)
- Validation of the radiometric correction described in [6] to check the first two factors influencing the intensity

$$I_{corrected} = I_{recorded} \times \left(\frac{R}{R_s}\right)^2 \times \frac{1}{cos(\alpha)}$$

$Icorrected$ = corrected intensity
$Irecorded$ = recorded intensity
R = recorded range
R_s = standard range
α = incidence angle

Radar-LiDAR coupling

Radar data specifications

- Sensor: Phased Array type L-band Synthetic Aperture Radar (PALSAR) on-board the ALOS Japanese satellite launched in January 2006
- Wavelength: 23.6 cm (frequency: 1.27 GHz)
- Repeat-pass: 46-day cycle
- Altitude: Approximately 692 km
- Spatial resolution: 18 m
- Polarisation: HH and HV
- Datasets: 9 amplitude images from March 2007 to October 2008 + 8 phase coherence images

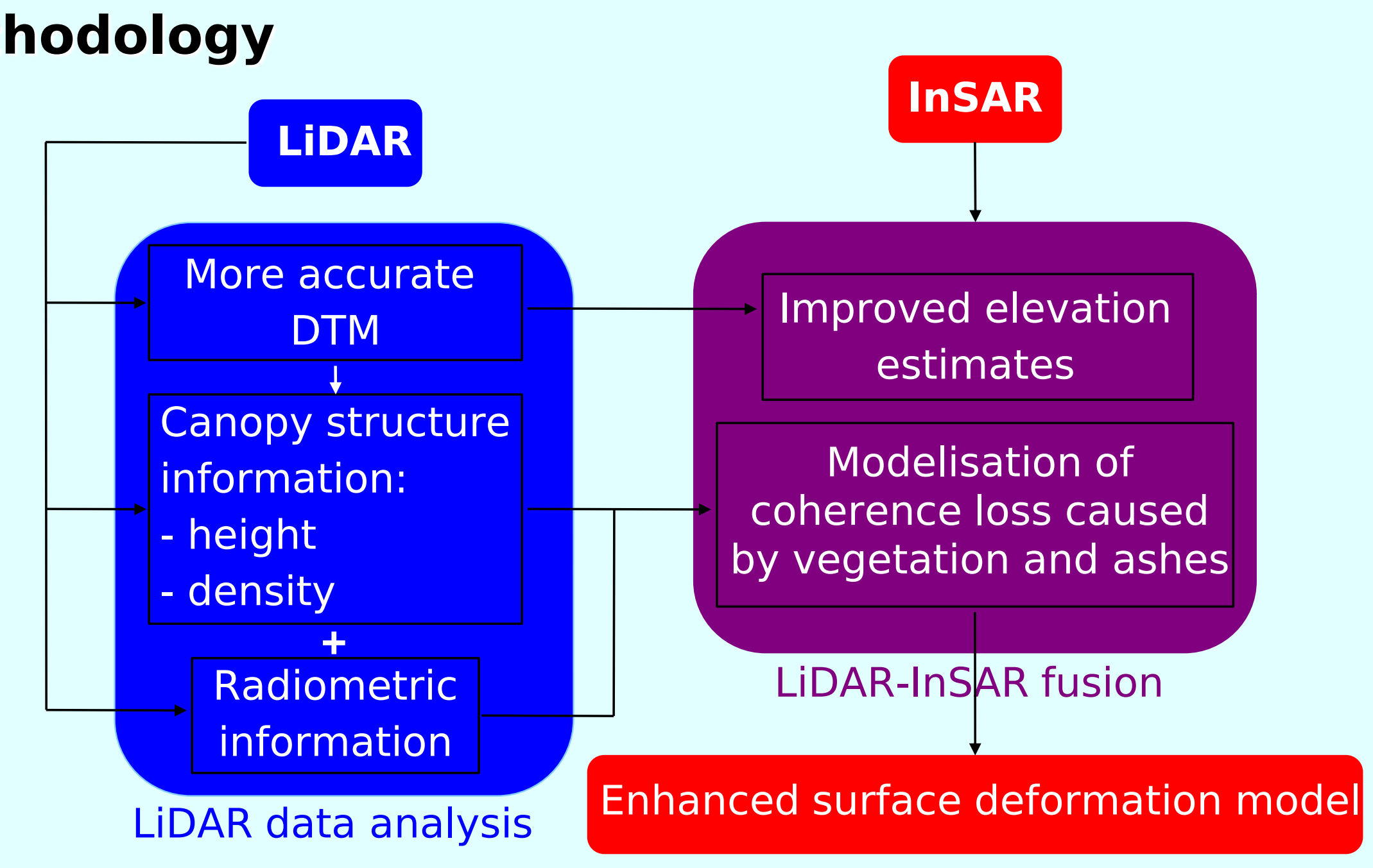
Coherence calculation = cross-correlation coefficient γ of the SAR image pair, $0 \leq |\gamma| \leq 1$

→ γ quantitatively describes the interferogram fringe reliability

$$\gamma = \frac{E\{y_1 {y_2}^*\}}{\sqrt{E\{{y_1}^2\}\ E\{{y_2}^2\}}}$$

where y_1 and y_2 are the phase and amplitude of the radar signal

Methodology



LiDAR

InSAR

More accurate DTM

Canopy structure information:
- height
- density

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Radiometric information

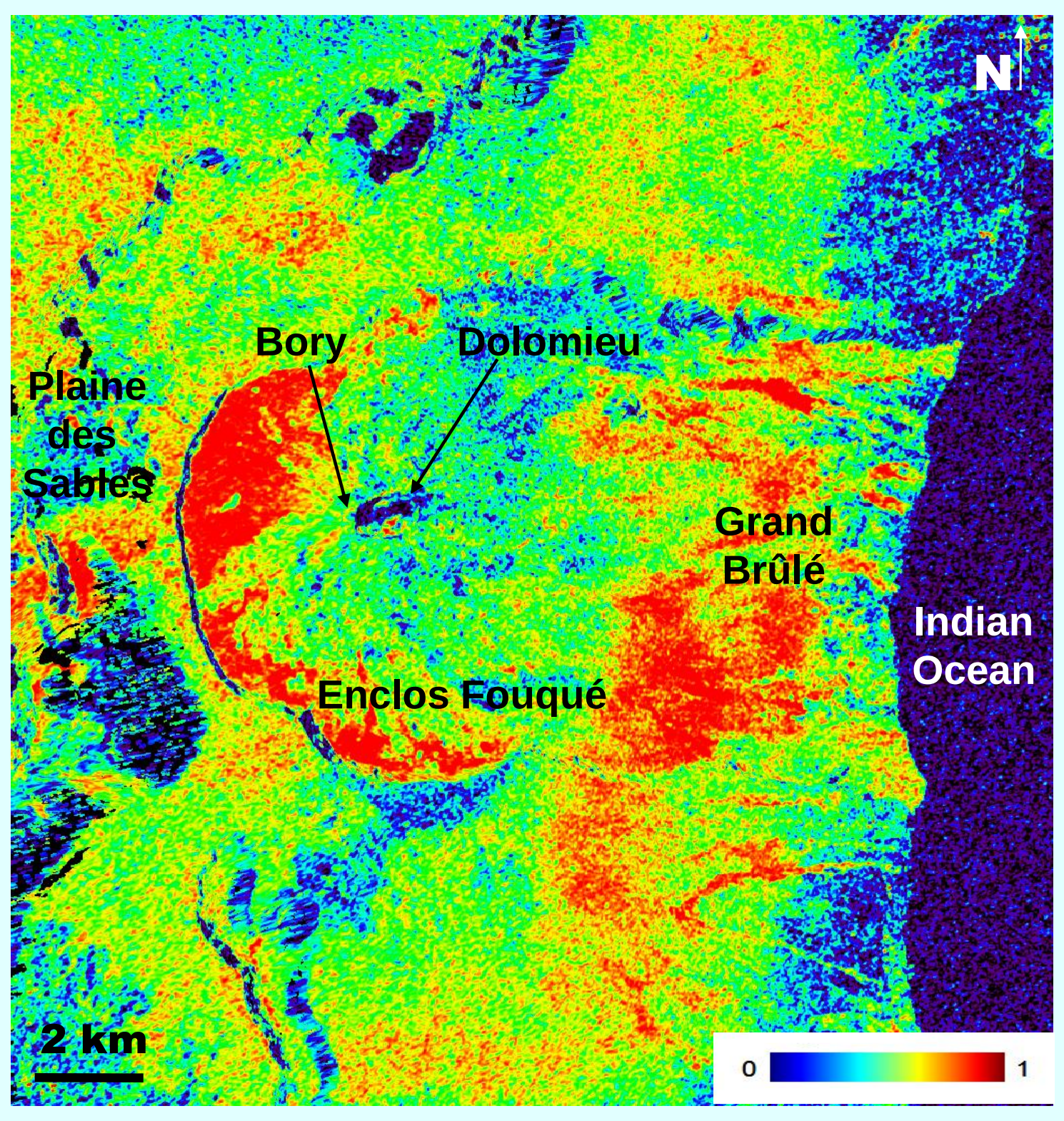
LiDAR data analysis

Improved elevation estimates

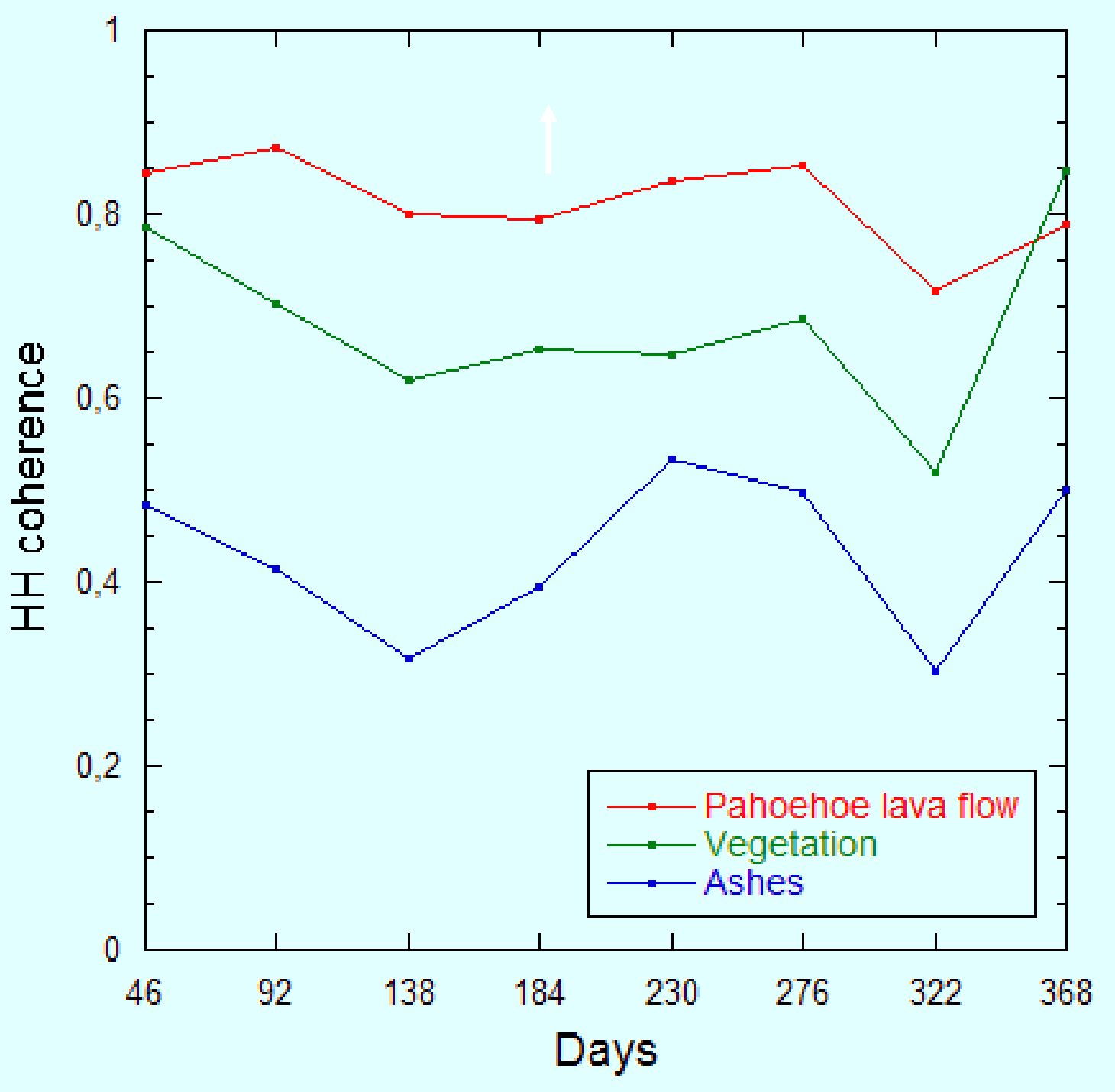
Modelisation of coherence loss caused by vegetation and ashes

LiDAR-InSAR fusion

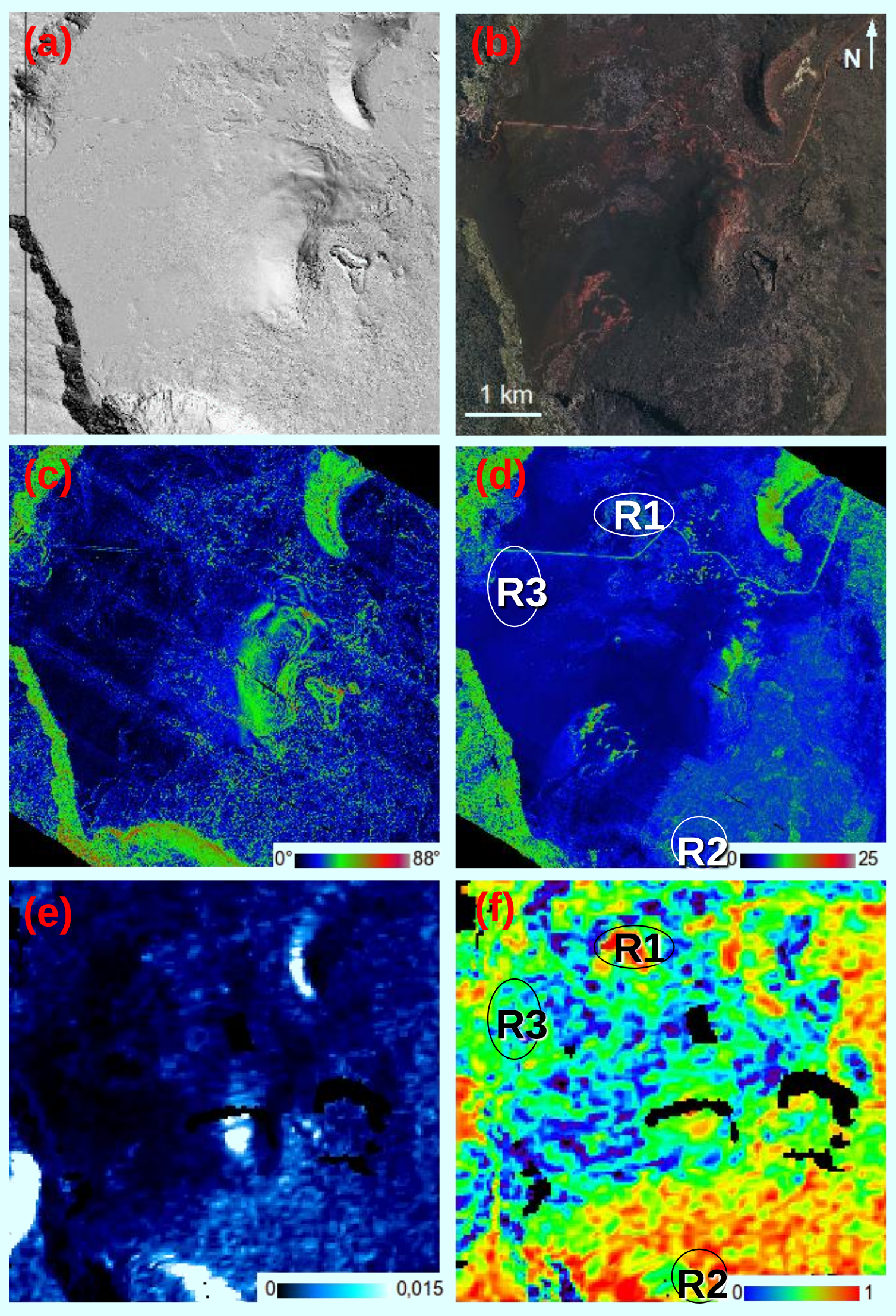
Enhanced surface deformation model



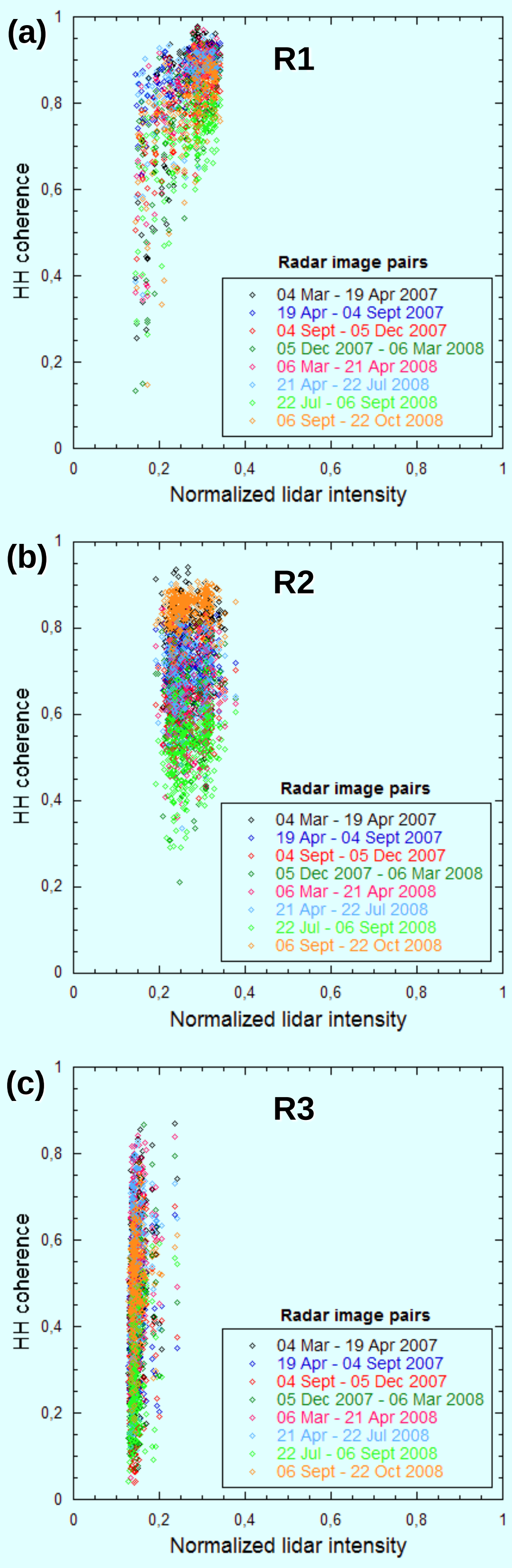
HH coherence map calculated between two successive images (06 Sept – 22 Oct 2008) Acquired over the Piton de La Fournaise.



HH coherence variations for different terrain types.



LiDAR and SAR maps of the Plaine des sables (NW flank of the edifice). (a) Shaded relief representation derived from the LiDAR data; (b) visible image; (c) slope map derived from the LiDAR data; (d) LiDAR intensity image; (e) HH amplitude map (22 Oct 2008); (f) HH coherence map (06 Sept – 22 Oct 2008).



Correlation between HH coherence and normalized lidar intensity for different terrain types. (a) R1 = pahoehoe lava flow; R2 = vegetation (bushes); R3 = volcanic ashes.

Preliminary conclusions

- SAR coherence variations are caused by the dielectric property modifications of pyroclastics and vegetation growth.
- L-band polarimetric data allow to minimize temporal decorrelation effects caused by vegetation covers but the signal penetration into pyroclasts is more important.
- The correlation between InSAR coherence and LiDAR intensity should enhance the analysis of the coherence over vegetated and pyroclastic active terrains: LiDAR data are expected to help overcome phase decorrelation due to vegetation and soil penetration in order to enhance the accuracy of early phase displacement maps.

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